

Alternation makes the adversary weaker in two-player games

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NeurIPS 2023, [Spotlight Paper](#)



joint work with



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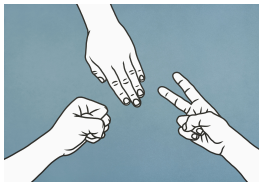
A. Kavis, **UT Austin**



L. Viano, **EPFL**

Normal Form Games

Rock-Paper-Scissors



Payoff matrix of Alice

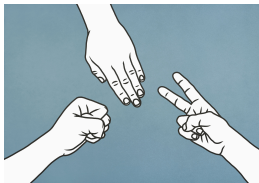
Alice/Bob	Rock	Paper	Scissors
Rock	0	-1	1
Paper	1	0	-1
Scissors	-1	1	0

Payoff matrix of Bob

Alice/Bob	Rock	Paper	Scissors
Rock	0	1	-1
Paper	-1	0	1
Scissors	1	-1	0

Normal Form Games

Rock-Paper-Scissors



Alice plays Rock

Alice/Bob	Rock	Paper	Scissors
Rock	0	-1	1
Paper	1	0	-1
Scissors	-1	1	0

Alice gets -1

Bob plays Scissors

Alice/Bob	Rock	Paper	Scissors
Rock	0	1	-1
Paper	-1	0	1
Scissors	1	-1	0

Bob gets 1

Normal Form Games

Normal-Form Games

Matrices A and B

Payoff matrix A of Alice

A/B	1	...	j	...	m
1	A_{11}	...	A_{1j}	...	A_{1m}
$\vdots$	$\vdots$	$\vdots$	...	$\vdots$	$\vdots$
i	A_{i1}	...	A_{ij}	...	A_{im}
$\vdots$	$\vdots$	$\vdots$	...	$\vdots$	$\vdots$
n	A_{n1}	...	A_{n2}	...	A_{nm}

Payoff matrix B of Bob

A/B	1	...	j	...	m
1	B_{11}	...	B_{1j}	...	B_{1m}
$\vdots$	$\vdots$	$\vdots$	...	$\vdots$	$\vdots$
i	B_{i1}	...	B_{ij}	...	B_{im}
$\vdots$	$\vdots$	$\vdots$	...	$\vdots$	$\vdots$
n	B_{n1}	...	B_{n2}	...	B_{nm}

Normal Form Games

Normal-Form Games

Matrices A and B

Alice plays action i

A/B	1	...	j	...	m
1	A_{11}	...	A_{1j}	...	A_{1m}
$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$
i	A_{i1}	...	A_{ij}	...	A_{im}
$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$
n	A_{n1}	...	A_{nj}	...	A_{nm}

Alice gets A_{ij}

Bob plays action j

A/B	1	...	j	...	m
1	B_{11}	...	B_{1j}	...	B_{1m}
$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$
i	B_{i1}	...	B_{ij}	...	B_{im}
$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$
n	B_{n1}	...	B_{nj}	...	B_{nm}

Bob gets B_{ij}

Normal Form Games

Normal-Form Games - Mixed Strategies

Matrices A and B

Alice plays a prob. distr.

$$x = (x_1, \dots, x_n) \in \Delta_n$$

A/B	1	...	j	...	m
1	A_{11}	...	A_{1j}	...	A_{1m}
$\vdots$	$\vdots$	$\vdots$	...	$\vdots$	$\vdots$
i	A_{i1}	...	A_{ij}	...	A_{im}
$\vdots$	$\vdots$	$\vdots$	...	$\vdots$	$\vdots$
n	A_{n1}	...	A_{n2}	...	A_{nm}

Bob plays a prob. distr.

$$y = (y_1, \dots, y_m) \in \Delta_m$$

A/B	1	...	j	...	m
1	B_{11}	...	B_{1j}	...	B_{1m}
$\vdots$	$\vdots$	$\vdots$	...	$\vdots$	$\vdots$
i	B_{i1}	...	B_{ij}	...	B_{im}
$\vdots$	$\vdots$	$\vdots$	...	$\vdots$	$\vdots$
n	B_{n1}	...	B_{n2}	...	B_{nm}

Normal Form Games

Normal-Form Games - Mixed Strategies

Matrices A and B

Alice plays a prob. distr.

$$x = (x_1, \dots, x_n) \in \Delta_n$$

A/B	1	...	j	...	m
1	A_{11}	...	A_{12}	...	A_{1m}
$\vdots$	$\vdots$	$\vdots$	...	$\vdots$	$\vdots$
i	A_{i1}	...	A_{ij}	...	A_{im}
$\vdots$	$\vdots$	$\vdots$	...	$\vdots$	$\vdots$
n	A_{n1}	...	A_{n2}	...	A_{nm}

Alice's expected cost

$$x^\top A y$$

Bob plays a prob. distr.

$$y = (y_1, \dots, y_m) \in \Delta_m$$

A/B	1	...	j	...	m
1	B_{11}	...	B_{12}	...	B_{1m}
$\vdots$	$\vdots$	$\vdots$	...	$\vdots$	$\vdots$
i	B_{i1}	...	B_{ij}	...	B_{im}
$\vdots$	$\vdots$	$\vdots$	...	$\vdots$	$\vdots$
n	B_{n1}	...	B_{n2}	...	B_{nm}

Bob's expected cost

$$x^\top B y$$

Normal Form Games

Normal-Form Games - Mixed Strategies

Matrices A and B

Alice plays a prob. distr.

$$x = (x_1, \dots, x_n) \in \Delta_n$$

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1	A_{11}	...	A_{1j}	...	A_{1m}
$\vdots$	$\vdots$	$\vdots$	...	$\vdots$	$\vdots$
i	A_{i1}	...	A_{ij}	...	A_{im}
$\vdots$	$\vdots$	$\vdots$	...	$\vdots$	$\vdots$
n	A_{n1}	...	A_{nj}	...	A_{nm}

$$x^\top A y$$

Bob plays a prob. distr.

$$y = (y_1, \dots, y_m) \in \Delta_m$$

A/B	1	...	j	...	m
1	B_{11}	...	B_{1j}	...	B_{1m}
$\vdots$	$\vdots$	$\vdots$	...	$\vdots$	$\vdots$
i	B_{i1}	...	B_{ij}	...	B_{im}
$\vdots$	$\vdots$	$\vdots$	...	$\vdots$	$\vdots$
n	B_{n1}	...	B_{nj}	...	B_{nm}

$$x^\top B y$$

Normal-Form Games over Time

- Alice and Bob play the normal-form game (A, B) over T rounds.
 - ▶ *Simultaneous play*: Agents simultaneously select their strategies at each round (very well-studied).
 - ▶ *Alternating play*: Agents alternatingly update their strategies (this work).

Simultaneous Play

Simultaneous Play

Bob challenges Alice to play (A, B) for T rounds.

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- Alice selects x_1 / Bob selects y_1

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Bob challenges Alice to play (A, B) for T rounds.

- Alice selects x_1 / Bob selects $y_1 \longrightarrow$ Alice gets $x_1^\top A y_1$

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Bob challenges Alice to play (A, B) for T rounds.

- Alice selects x_1 / Bob selects $y_1 \longrightarrow$ Alice gets $x_1^\top A y_1$
- Alice selects x_2 / Bob selects y_2

Simultaneous Play

Simultaneous Play

Bob challenges Alice to play (A, B) for T rounds.

- Alice selects x_1 / Bob selects $y_1 \longrightarrow$ Alice gets $x_1^\top A y_1$
- Alice selects x_2 / Bob selects $y_2 \longrightarrow$ Alice gets $x_2^\top A y_2$

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Bob challenges Alice to play (A, B) for T rounds.

- Alice selects x_1 / Bob selects $y_1 \longrightarrow$ Alice gets $x_1^\top A y_1$
- Alice selects x_2 / Bob selects $y_2 \longrightarrow$ Alice gets $x_2^\top A y_2$
- Alice selects x_3 / Bob selects y_3

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- Alice selects x_3 / Bob selects $y_3 \longrightarrow$ Alice gets $x_3^\top A y_3$
- ...

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- ...

How should Alice select her actions over time?

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Simultaneous Play

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- **Alice** selects x_1 / **Bob** selects $y_1 \rightarrow$ **Alice** gets $x_1^\top A y_1$
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- **Alice** selects x_3 / **Bob** selects $y_3 \rightarrow$ **Alice** gets $x_3^\top A y_3$
- ...

How should **Alice** select her actions over time? *No Regret algorithms*

- Regret Matching [Blackwell '65]
- Hedge [Freund et al. '97]
- Online Gradient Descent [Zinkevich '03]
- Follow the Regularized Leader [Abernethy et al. '10]
-

Simultaneous play

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- ...

Hedge Algorithm [Freund and Schapire '97] Godel Prize '03

$$x_{t+1}(i) = \frac{x_t(i) \cdot e^{-\gamma[Ay_t]_i}}{\sum_{j=1}^n x_t(j) \cdot e^{-\gamma[Ay_t]_j}}$$

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Theorem (**Freund and Schapire JCSS '97**)

No matter Bob's strategies $y_1, \dots, y_T$, the regret of Alice $\mathcal{R}(T)$

$$\mathcal{R}(T) := \underbrace{\sum_{t=1}^T x_t^\top A y_t}_{\text{cost of Alice}} - \underbrace{\min_{i \in [n]} \sum_{t=1}^T [Ay_t]_i}_{\text{cost of best action}} \leq \tilde{O}(\sqrt{T})$$

Simultaneous play

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- **Alice** selects x_2 / **Bob** selects $y_2 \rightarrow$ **Alice** gets $x_2^\top A y_2$
- **Alice** selects x_3 / **Bob** selects $y_3 \rightarrow$ **Alice** gets $x_3^\top A y_3$
- ...

Theorem (Freund and Schapire JCSS '97)

No matter Bob's strategies,

$$\underbrace{\frac{1}{T} \sum_{t=1}^T x_t^\top A y_t}_{\text{time-average cost}} \leq \underbrace{\frac{1}{T} \min_{x \in \Delta_n} \sum_{t=1}^T x^\top A y_t}_{\text{best fixed action}} + \tilde{O}\left(\frac{\sqrt{T}}{T}\right) \rightarrow 0$$

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Can Alice do better?

Simultaneous play

Simultaneous Play

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Can Alice do better? **No!**

Simultaneous play

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- ...

Theorem (folklore)

Bob can always select $y_1, \dots, y_T$, *the regret of Alice*

$$\mathcal{R}(T) := \underbrace{\sum_{t=1}^T x_t^\top A y_t}_{\text{cost of Alice}} - \underbrace{\min_{i \in [n]} \sum_{t=1}^T [A y_t]_i}_{\text{cost of best action}} \geq \Omega(\sqrt{T})$$

$\mathcal{O}(\sqrt{T})$ regret is the best **Alice** can get in **simultaneous play**!

Regret Lower Bound on Simultaneous play

- Let $A = \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}$ and $B = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$.

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- No matter what $x_t \in \Delta_n$ **Alice** selects,

$$\mathbb{E}[x_t^\top A y_t] = 0 \text{ and thus } \sum_{t=1}^T \mathbb{E}[x_t^\top A y_t] = 0$$

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- However $\min_{i \in \{1,2\}} [A y_t]_i = -\Theta(\sqrt{T})$ since $[A y_t]_i = 1$ or -1 with probability $1/2$.

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$$\mathbb{E}[x_t^\top A y_t] = 0 \text{ and thus } \sum_{t=1}^T \mathbb{E}[x_t^\top A y_t] = 0$$

- However $\min_{i \in \{1,2\}} [A y_t]_i = -\Theta(\sqrt{T})$ since $[A y_t]_i = 1$ or -1 with probability $1/2$.
- No matter how **Alice** her sequence $x_1, \dots, x_T$:

$$\mathbb{E} \left[\sum_{t=1}^T x_t^\top A y_t - \min_{i \in [n]} \sum_{t=1}^T [A y_t]_i \right] = \Theta(\sqrt{T})$$

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- **Alice** selects x_2 / **Bob** selects $y_2 \longrightarrow$ **Alice** gets $x_2^\top A y_2$
- ...

Theorem (folklore)

Bob can always select $y_1, \dots, y_T$, the regret of Alice

$$\mathcal{R}(T) := \underbrace{\sum_{t=1}^T x_t^\top A y_t}_{\text{cost of Alice}} - \underbrace{\min_{i \in [n]} \sum_{t=1}^T [A y_t]_i}_{\text{cost of best action}} \geq \Omega(\sqrt{T})$$

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What if Alice and Bob play in alternating turns?

Solving Heads'up Poker



Online Learning + Simultaneous Play

Polaris [Bowling et al. AAMAS '09] → Decent Performance

Solving Heads'up Poker



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Online Learning + Alternating Play

Cepheus [Oskari et al. IJCAI '15], Libratus [Brown et al. IJCAI '17] → **Beat Human Experts!**

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Regret Guarantees → Faster Training!

Alternating Turns

Alternating Play

Bob challenges **Alice** to play (A, B) for T rounds in **alternating turns**.

Alternating Turns

Alternating Play

Bob challenges Alice to play (A, B) for T rounds in **alternating turns**.

- Bob selects y_0

Alternating Turns

Alternating Play

Bob challenges Alice to play (A, B) for T rounds in **alternating turns**.

- Bob selects y_0
- Alice selects x_1

Alternating Turns

Alternating Play

Bob challenges Alice to play (A, B) for T rounds in **alternating turns**.

- Bob selects y_0
- Alice selects $x_1 \longrightarrow$ Alice gets $x_1^\top A y_0$

Alternating Turns

Alternating Play

Bob challenges Alice to play (A, B) for T rounds in **alternating turns**.

- Bob selects y_0
- Alice selects $x_1 \longrightarrow$ Alice gets $x_1^\top A y_0$
- Bob selects y_2

Alternating Turns

Alternating Play

Bob challenges **Alice** to play (A, B) for T rounds in **alternating turns**.

- **Bob** selects y_0
- **Alice** selects $x_1 \longrightarrow$ **Alice** gets $x_1^\top A y_0$
- **Bob** selects $y_2 \longrightarrow$ **Alice** gets $x_1^\top A y_2$

Alternating Turns

Alternating Play

Bob challenges Alice to play (A, B) for T rounds in **alternating turns**.

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- Alice selects $x_1 \longrightarrow$ Alice gets $x_1^\top A y_0$
- Bob selects $y_2 \longrightarrow$ Alice gets $x_1^\top A y_2$
- Alice selects x_3

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- **Alice** selects $x_3 \longrightarrow$ **Alice** gets $x_3^\top A y_2$

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- ...

Can **Alice** have regret $\mathcal{R}(T)$ better than $\mathcal{O}(\sqrt{T})$?

$$\mathcal{R}(T) := \underbrace{\sum_{k=0}^{T/2} x_{2k+1}^\top A(y_{2k} + y_{2k+2})}_{\text{Alice's cost}} - \underbrace{\min_{x \in \Delta_n} \sum_{k=0}^{T/2} x^\top A(y_{2k} + y_{2k+2})}_{\text{best fixed action}}$$

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Previous $\Omega(\sqrt{T})$ lower bound fails!

Regret Lower Bound Fails!!!

- Let $A = \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}$ and $B = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$.

Regret Lower Bound Fails!!!

- Let $A = \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}$ and $B = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$.
- **Bob** is indifferent so it selects $y_t = (1, 0)$ or $(0, 1)$ with prob. $1/2$.
- **Alice** selects $x_t = (1, 0)$ if $y_{t-1} = (1, 0)$ and $x_t = (0, 1)$ if $y_{t-1} = (0, 1)$.

Thus,

$$\sum_{t=1}^T \mathbb{E}[x_t^\top A(y_{t-1} + y_t)] = -T$$

Regret Lower Bound Fails!!!

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- However $\min_{i \in \{1,2\}} [A(y_t + y_{t-1})]_i = -\Theta(\sqrt{T})$ since $[Ay_t]_i = 1$ or -1 with probability $1/2$.
- No matter how **Alice** her sequence $x_1, \dots, x_T$:

$$\mathbb{E} \left[\sum_{t=1}^T x_t^\top A(y_t + y_{t-1}) - \min_{i \in [n]} \sum_{t=1}^T [A(y_t + y_{t-1})]_i \right] = -T + \Theta(\sqrt{T})$$

Alternating Turns

Alternating Play

Bob challenges **Alice** to play (A, B) for T rounds in **alternating turns**.

- **Bob** selects y_0
- **Alice** selects $x_1 \rightarrow$ **Alice** gets $x_1^\top A y_0$
- **Bob** selects $y_2 \rightarrow$ **Alice** gets $x_1^\top A y_2$
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- ...

Can **Alice** have regret $\mathcal{R}(T)$ better than $\mathcal{O}(\sqrt{T})$?

$$\mathcal{R}(T) := \underbrace{\sum_{k=0}^{T/2} x_{2k+1}^\top A(y_{2k} + y_{2k+2})}_{\text{Alice's cost}} - \underbrace{\min_{x \in \Delta_n} \sum_{k=0}^{T/2} x^\top A(y_{2k} + y_{2k+2})}_{\text{best fixed action}}$$

Previous $\Omega(\sqrt{T})$ lower bound fails!

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Theorem (Skoulakis et al., NeurIPS '23 spotlight)

In alternating play, Alice can always guarantee

- $\tilde{\mathcal{O}}(T^{1/3})$ regret for general games.
- $\mathcal{O}(\log T)$ for $n = 2$ actions (different algorithm).

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Previous Results

- If **both** Alice and Bob use *Gradient Descent* in **unconstrained zero-sum games** $\rightarrow \mathcal{O}(1)$ regret [Bailey et al. COLT 2020]
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Our algorithm (general simplex)

$$x_{2k+1} \leftarrow \operatorname{argmin}_{x \in \Delta_n} \left[3 \underbrace{x^\top A y_{2k}}_{\text{exploits } y_{2k}} + \underbrace{2 \sum_{k'=0}^{k-1} x^\top A y_{2k'}}_{\text{reinforces good past actions}} - \underbrace{\gamma \cdot \sum_{i=1}^n \log x_i}_{\text{prevents overfitting}} \right]$$

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Setting $\gamma = \mathcal{O}(T^{1/3}) \rightarrow \mathcal{O}(T^{1/3})$ alternating regret

Our Algorithm (General Case)

Algorithm 1: Our method

1: **for** rounds $t = 1, \dots, T$ **do**

2: **Alice** selects sets $c_t \rightarrow Ay_t$ and selects the mixed strategy $x_t \in \Delta_2$,

$$x_t := \operatorname{argmin}_{x \in \Delta_n} \left[2\gamma c_{t-1}^\top x + \gamma \sum_{s=1}^{t-1} (c_s + c_{s-1})^\top x - \underbrace{\sum_{i=1}^2 \log x_i / \gamma}_{\text{log-barrier penalty}} \right]$$

3: **Alice** suffers cost $(c_t + c_{t-1})^\top x_t$

4: **end for**

Analysis

Be the Regularized Leader

Let $y_{t+1} := \min_{x \in \Delta_n} [\gamma(c_t + c_{t-1})^\top x + \gamma \sum_{s=1}^{t-1} (c_s + c_{s-1})^\top x - \sum_{i=1}^2 \log x_i]$.

Then,

$$\sum_{t=1}^T (c_t + c_{t-1})^\top \cdot y_{t+1} - \min_{x \in \Delta_n} \sum_{t=1}^T (c_t + c_{t-1})^\top \cdot x \leq \mathcal{O}\left(\frac{\log T}{\gamma}\right)$$

◦ Regret Decomposition

$$\begin{aligned} & \sum_{t=1}^T (c_{t-1} + c_t)^\top (x_t - x^\star) \\ &= \underbrace{\sum_{t=1}^T (c_{t-1} + c_t)^\top (y_{t+1} - x^\star)}_{\leq \mathcal{O}(\log T / \gamma)} + \sum_{t=1}^T (c_{t-1} + c_t)^\top (x_t - y_{t+1}) \end{aligned}$$

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Analysis

In order to control $\sum_{t=1}^T (c_{t-1} + c_t)^\top (x_t - y_{t+1})$, we notice that

$$\begin{aligned} \bullet \quad y_{t+1} &:= \min_{x \in \Delta_2} \underbrace{\left[\gamma(c_t + c_{t-1})^\top x + \gamma \sum_{s=1}^{t-1} (c_s + c_{s-1})^\top x - \sum_{i=1}^2 \log x_i \right]}_{\text{Be the Leader}} \\ \bullet \quad x_t &:= \min_{x \in \Delta_2} \underbrace{\left[2\gamma c_{t-1}^\top x + \gamma \sum_{s=1}^{t-1} (c_s + c_{s-1})^\top x - \sum_{i=1}^2 \log x_i \right]}_{\text{our Algorithm}} \end{aligned}$$

Lemma (Skoulakis et al., 2023)

Let $x_t, y_{t+1} \in \Delta_n$ defined as above. Then,

$$x_t - y_{t+1} = \gamma \cdot A(x_t, y_{t+1})(c_t - c_{t-1})$$

where $A(x, y)$ is an $n \times n$ matrix with

$$\|A(x, y) - A(x', y')\|_2 \leq \mathcal{O}(1) \cdot \|(x, y) - (x', y')\|_2.$$

Analysis

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2 action simplex

- If Alice admits 2 actions $\rightarrow \mathcal{O}(\log T)$ in alternating play!

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- Alice plays x_{2k+1} in the convex hull of z_k and w_k .

Take-Away Message



Algorithms beyond $\mathcal{O}(\sqrt{T})$ regret lower bounds of simultaneous play.

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Thank you!!